

The complexity of Gaussian conditional independence models

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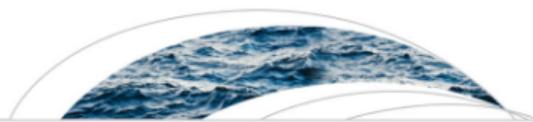
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Question: When can we conclude from some independences other independences?

E.g., is it possible that $c_1 \perp\!\!\!\perp b$?



Water Resources Research

RESEARCH ARTICLE **A Statistical Graphical Model of the California Reservoir System**

10.1002/2017WR020412

Key Points:

- We develop a statistical graphical model to characterize the statewide California reservoir system
- We quantify the influence of external physical and economic factors (e.g., statewide PDSI and consumer price index) on the reservoir network
- Further analysis gives a system-wide health diagnosis as a function of PDSI, indicating when heavy management practices may be needed

Supporting Information:

- Supporting Information S1
- Supporting Information S2

A. Taeb¹ , **J. T. Reager²** , **M. Turmon²** , and **V. Chandrasekaran³**

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Abstract The recent California drought has highlighted the potential vulnerability of the state's water management infrastructure to multiyear dry intervals. Due to the high complexity of the network, dynamic storage changes in California reservoirs on a state-wide scale have previously been difficult to model using either traditional statistical or physical approaches. Indeed, although there is a significant line of research on exploring models for single (or a small number of) reservoirs, these approaches are not amenable to a system-wide modeling of the California reservoir network due to the spatial and hydrological heterogeneities of the system. In this work, we develop a state-wide statistical graphical model to characterize the dependencies among a collection of 55 major California reservoirs across the state; this model is defined with respect to a graph in which the nodes index reservoirs and the edges specify the

Gaussian conditional independence

Assume $\xi = (\xi_i : i \in N)$ are jointly Gaussian with covariance matrix $\Sigma \in \text{PD}_N$.

Definition

The polynomial $\Sigma[K] := \det \Sigma_{K,K}$ is a *principal minor* of Σ and $\Sigma[ij | K] := \det \Sigma_{iK,jK}$ is an *almost-principal minor*.

- ▶ Σ is PD if and only if $\Sigma[K] > 0$ for all $K \subseteq N$.
- ▶ $[\xi_i \perp\!\!\!\perp \xi_j \mid \xi_K]$ holds if and only if $\Sigma[ij | K] = 0$.
- ▶ $\mathbb{E}[\xi] = \mu$ is irrelevant.

Very special polynomials

$$\Sigma[ij |] = x_{ij}$$

$$\Sigma[ij | k] = x_{ij}x_{kk} - x_{ik}x_{jk}$$

$$\Sigma[ij | kl] = x_{ij}x_{kk}x_{ll} - x_{il}x_{jl}x_{kk} + x_{il}x_{jk}x_{kl} + x_{ik}x_{jl}x_{kl} - x_{ij}x_{kl}^2 - x_{ik}x_{jk}x_{ll}$$

$$\begin{aligned}\Sigma[ij | klm] = & x_{ij}x_{kk}x_{ll}x_{mm} + x_{im}x_{jm}x_{kl}^2 - x_{im}x_{jl}x_{kl}x_{km} - x_{il}x_{jm}x_{kl}x_{km} + \\ & x_{il}x_{jl}x_{km}^2 - x_{im}x_{jm}x_{kk}x_{ll} + x_{im}x_{jk}x_{km}x_{ll} + x_{ik}x_{jm}x_{km}x_{ll} - \\ & x_{ij}x_{km}^2x_{ll} + x_{im}x_{jl}x_{kk}x_{lm} + x_{il}x_{jm}x_{kk}x_{lm} - x_{im}x_{jk}x_{kl}x_{lm} - \\ & x_{ik}x_{jm}x_{kl}x_{lm} - x_{il}x_{jk}x_{km}x_{lm} - x_{ik}x_{jl}x_{km}x_{lm} + 2x_{ij}x_{kl}x_{km}x_{lm} + \\ & x_{ik}x_{jk}x_{lm}^2 - x_{ij}x_{kk}x_{lm}^2 - x_{il}x_{jl}x_{kk}x_{mm} + x_{il}x_{jk}x_{kl}x_{mm} + \\ & x_{ik}x_{jl}x_{kl}x_{mm} - x_{ij}x_{kl}^2x_{mm} - x_{ik}x_{jk}x_{ll}x_{mm}\end{aligned}$$

⋮

Gaussian CI models

Definition

A *CI constraint* is a CI statement $[\xi_i \perp\!\!\!\perp \xi_j \mid \xi_K]$ or its negation $\neg[\xi_i \perp\!\!\!\perp \xi_j \mid \xi_K]$.

The *model* of a set of CI constraints is the set of all PD matrices which satisfy them.

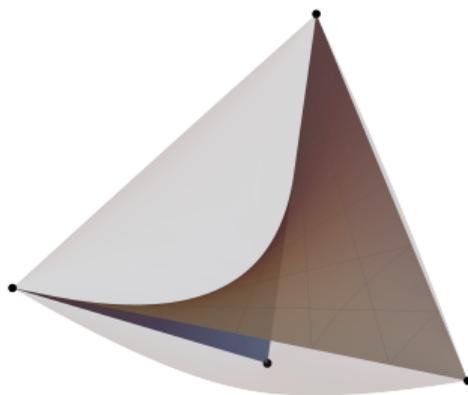


Figure: Model of $\Sigma[12|3] = a - bc = 0$ in the space of 3×3 correlation matrices.

Basic questions

- ▶ How hard is it to decide if the model specification is inconsistent?
- ▶ How hard is it to *certify* consistency by showing a point in the model?
- ▶ What is the geometric structure of the models?

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- ▶ What is the geometric structure of the models?

What is the model of $[X \perp\!\!\!\perp Y] \wedge [X \perp\!\!\!\perp Z \mid Y] \wedge \neg[X \perp\!\!\!\perp Y \mid Z]$?

Models and inference

Consider two sets of CI statements \mathcal{P} and \mathcal{Q} :

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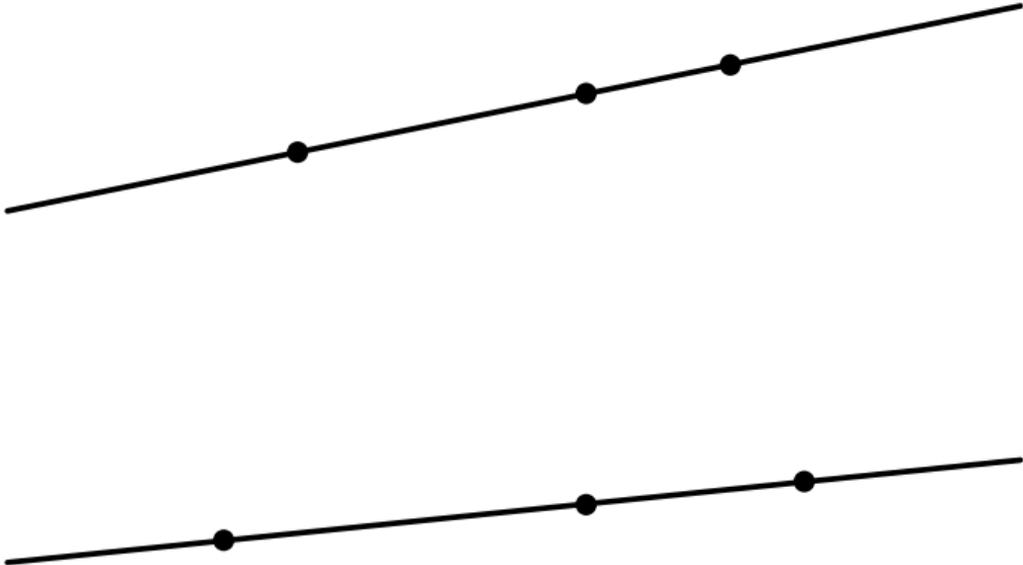
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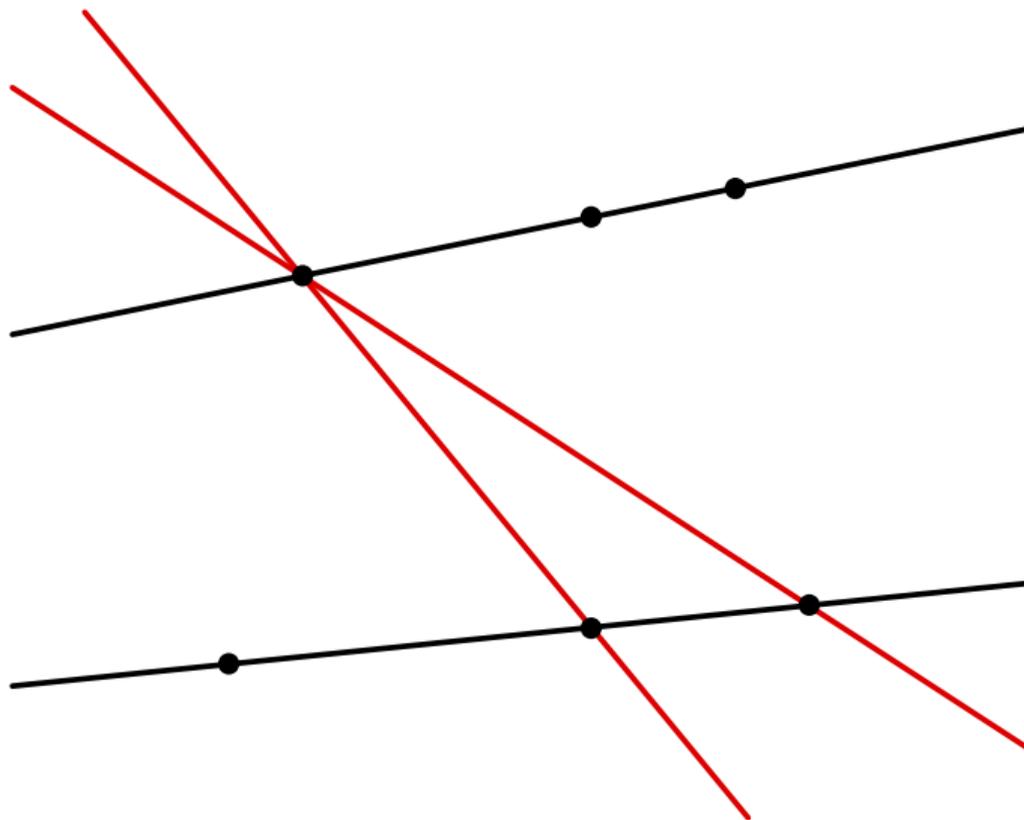
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Reasoning about CI statements in normally distributed random variables is **the same** as reasoning about the vanishing of very special kinds of determinants on very special kinds of varieties inside the positive definite matrices.

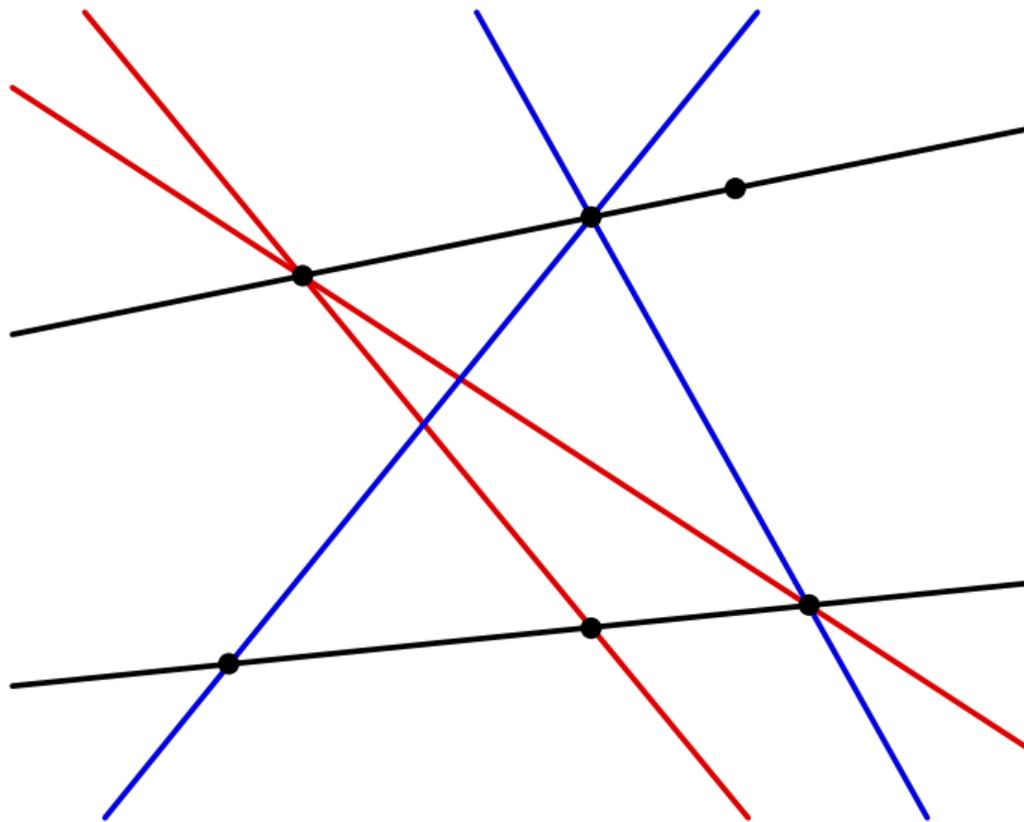
For ancient geometers: conditional independence \approx collinearity



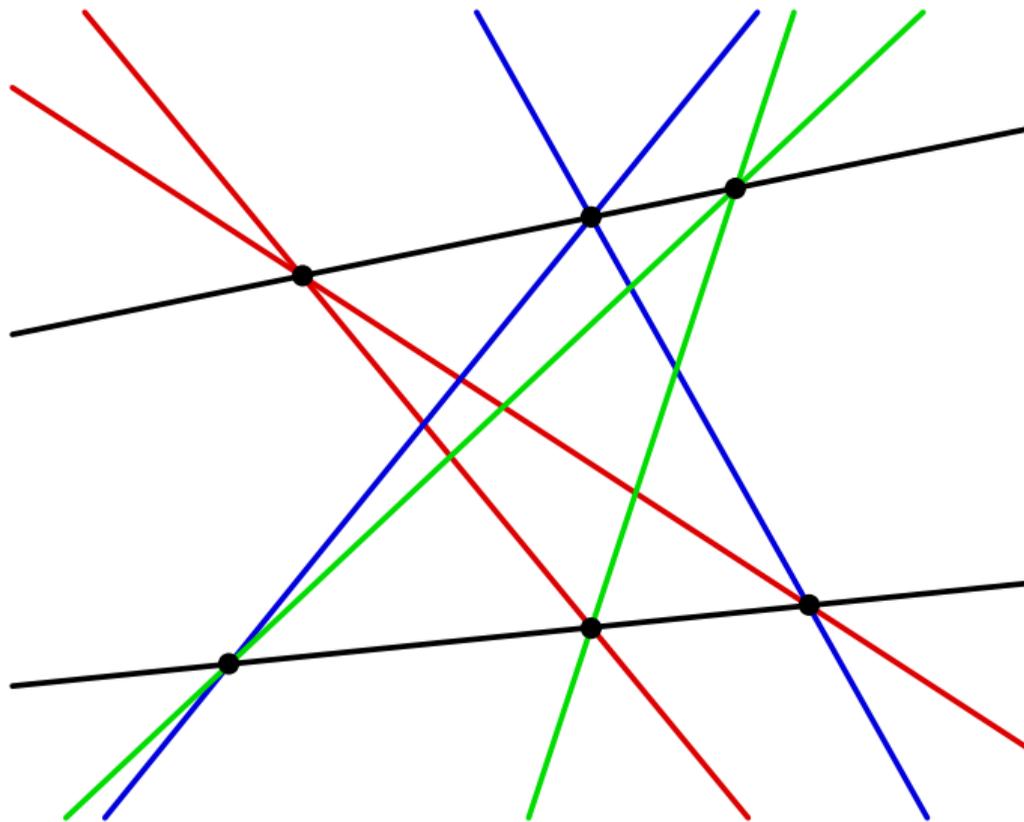
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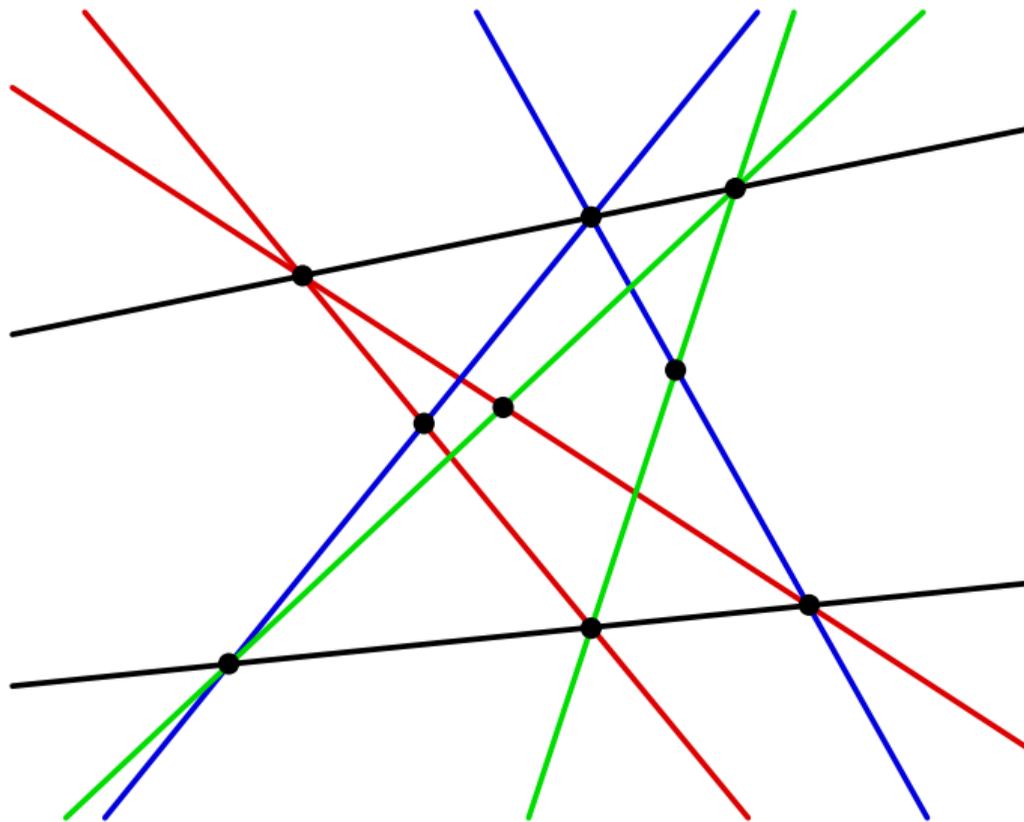
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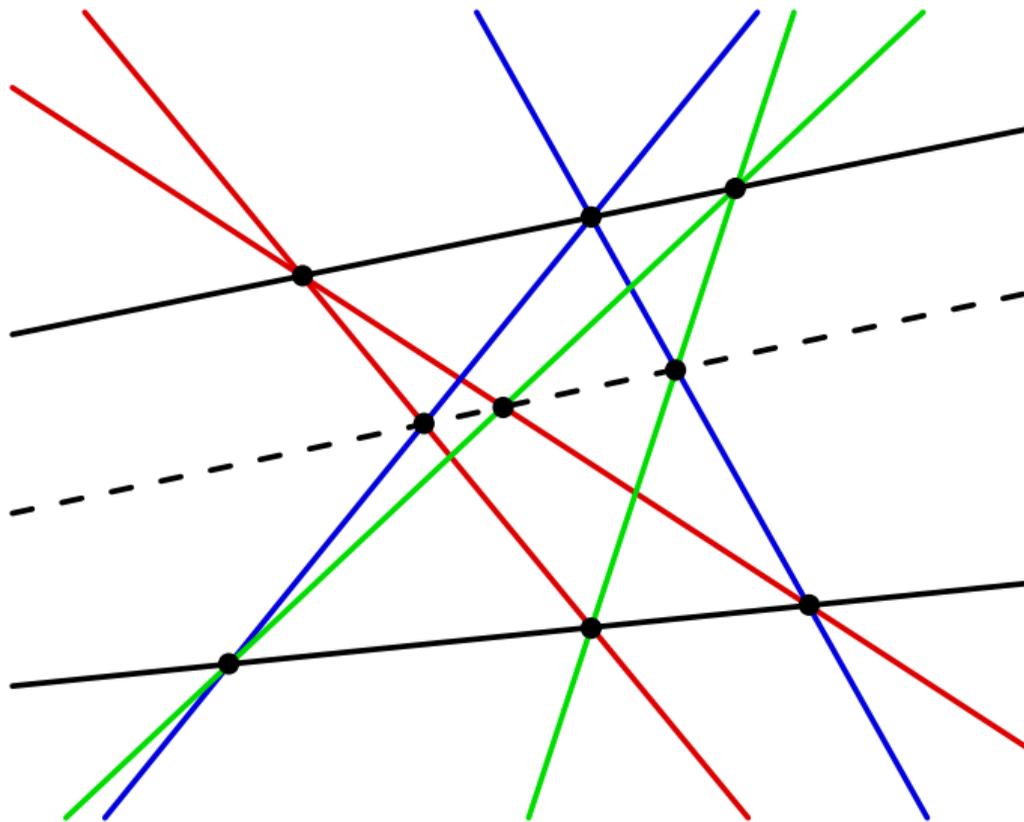
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Normal form for proofs and refutations

Let $f_i \in \mathbb{Z}[t_1, \dots, t_k]$ be integer polynomials in finitely many variables.

Theorem (Tarski's transfer principle)

If a polynomial system $\{f_i \bowtie_i 0\}$, where $\bowtie_i \in \{=, \neq, <, \leq, \geq, >\}$, has a solution over \mathbb{R} , then it has a solution in a finite real extension of \mathbb{Q} .

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→ If $\bigwedge \mathcal{P} \Rightarrow \bigvee \mathcal{Q}$ is false, there exists a counterexample matrix Σ with algebraic entries.

$[12|] \wedge [12|3] \Rightarrow [13|]$ is false and a counterexample is

$$\begin{pmatrix} 1 & 0 & 1/2 \\ 0 & 1 & 0 \\ 1/2 & 0 & 1 \end{pmatrix}.$$

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Let $f_i, g_j, h_k \in \mathbb{Z}[t_1, \dots, t_k]$ be integer polynomials in finitely many variables.

Theorem (Positivstellensatz)

A polynomial system $\{f_i = 0, g_j \geq 0, h_k \neq 0\}$ is infeasible if and only if there exist $f \in \text{ideal}(f_i)$, $g \in \text{cone}(g_j)$ and $h \in \text{monoid}(h_k)$ such that $g + h^2 = f$.

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→ If $\bigwedge \mathcal{P} \Rightarrow \bigvee \mathcal{Q}$ is **true**, there exists an algebraic proof for it with integer coefficients.

$[12 \mid] \wedge [12 \mid 3] \Rightarrow [13 \mid] \vee [23 \mid]$ is true and a proof is the **final polynomial**

$$\Sigma[13 \mid] \cdot \Sigma[23 \mid] = \Sigma[3] \cdot \Sigma[12 \mid] - \Sigma[12 \mid 3].$$

Computer algebra proves laws of probabilistic reasoning

The following inference rule is valid for all positive definite 5×5 matrices:

$$[12|] \wedge [14|5] \wedge [23|5] \wedge [35|1] \wedge [45|2] \wedge [15|23] \wedge [34|12] \wedge [24|135] \Rightarrow [25|] \vee [34|].$$

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$$[12 |] \wedge [14 | 5] \wedge [23 | 5] \wedge [35 | 1] \wedge [45 | 2] \wedge [15 | 23] \wedge [34 | 12] \wedge [24 | 135] \Rightarrow [25 |] \vee [34 |].$$

$$\begin{aligned} & [25 |] [34 |] \cdot [1] [2] [3] [15] = \\ & (cd^2egr + bd^2fgr - ad^2grh - 2cd^2e^2i - 2bd^2efi - 2pdfgri + 2ad^2ehi + 2pdefi^2 - 2pdqhi^2 + 2pcqi^3 + \\ & 2pdqrij - 2pbqi^2j - pcegrt + pbfgrt + pagrht + 2pce^2it - 2pcqrit + 2pbqhit - 2paehit) \cdot [12 |] + \\ & (pdqer + pbqgr - 2pbqei) \cdot [14 | 5] - (pcdqr + p^2fgr - 2pbcqi + 2pb^2qj - 2p^2qrj) \cdot [23 | 5] + \\ & (cdqgr - 2cdqei + 2pqghi - 2pqfi^2 - pqgrj + 2pqueij - 2pe^2ft + 2pqfrit) \cdot [35 | 1] + \\ & (pd^2er - 2pbdei + p^2gri + 2pb^2et - 2p^2ert) \cdot [45 | 2] - (2pdfi - 2pbft) \cdot [15 | 23] - \\ & (d^2gr - 2d^2ei - pgrt + 2peit) \cdot [34 | 12] - 2pqi \cdot [24 | 135]. \end{aligned}$$

Computer algebra proves laws of probabilistic reasoning

```
R = QQ[p,a,b,c,d, q,e,f,g, r,h,i, s,j, t];
X = genericSymmetricMatrix(R,p,5);
I = ideal(
  det X_{0}^{1}, det X_{0,3}^{2,3}, det X_{0,4}^{3,4},
  det X_{1,4}^{2,4}, det X_{2,0}^{4,0}, det X_{3,1}^{4,1},
  det X_{0,1,2}^{4,1,2}, det X_{2,0,1}^{3,0,1},
  det X_{1,0,2,4}^{3,0,2,4}
);
U = g*h*p*q*r*(p*t-d^2); -- [25|][34|] · [1][2][3][15] ∈ monoid(V)
U % I --> 0, meaning monoid(V) ∩ ideal(V) ≠ ∅ in Q[X]
-- Get a proof that U is in I:
G = gens I; -- the equations generating ideal(V)
H = U // G; -- linear combinators for U from G
U == G*H --> true
```

Consistency checking is hard

The complexity class $\exists\mathbb{R}$ contains all decision problems which can be reduced in polynomial time to the feasibility of a semialgebraic set:

- ▶ polynomial optimization
- ▶ computational geometry
- ▶ algebraic statistics . . .

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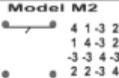
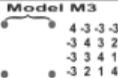
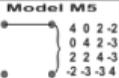
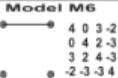
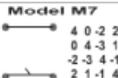
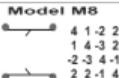
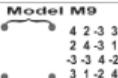
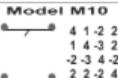
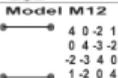
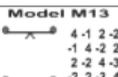
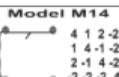
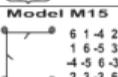
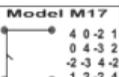
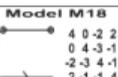
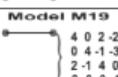
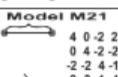
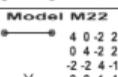
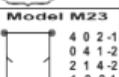
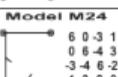
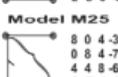
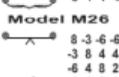
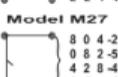
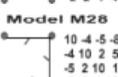
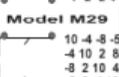
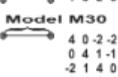
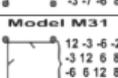
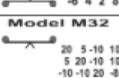
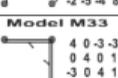
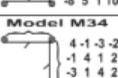
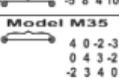
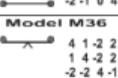
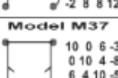
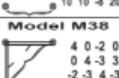
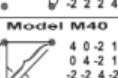
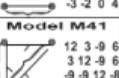
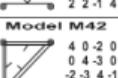
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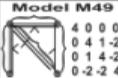
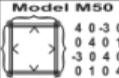
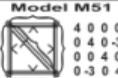
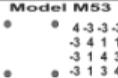
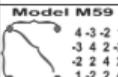
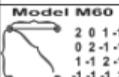
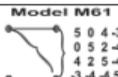
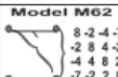
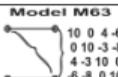
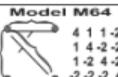
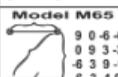
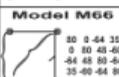
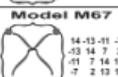
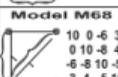
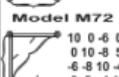
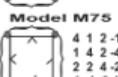
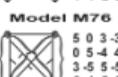
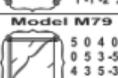
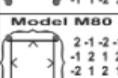
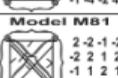
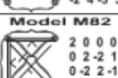
Theorem

The problem of deciding whether a general CI model is non-empty is complete for $\exists\mathbb{R}$.

(Graphical models are always consistent.)

Certification of consistency

 4 0 2 -2 0 4 1 -3 2 1 4 -3 -2 -3 -3 4	 4 1 -3 2 1 4 -3 2 -3 3 4 -1 2 2 -3 4	 4 -3 -3 -3 -3 4 3 2 -3 3 4 -1 -3 2 1 4	 4 0 1 -1 0 4 1 1 1 1 4 1 -1 1 1 4	 4 0 2 -2 0 4 2 -3 2 1 4 -3 -2 -3 -3 4	 4 0 3 -2 0 4 2 -3 3 2 4 -3 -2 -3 -3 4
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 12 -3 -6 -2 -3 12 6 8 -6 6 12 8 -2 8 8 12	 20 5 -10 10 5 20 -10 10 -10 -10 20 -8 10 10 -8 20	 4 0 -3 -3 0 4 0 1 -3 0 4 1 -3 1 1 4	 4 -1 -3 -2 -1 4 1 2 -3 1 4 2 -2 2 2 4	 4 0 -2 -3 0 4 3 -2 -2 3 4 0 -3 2 0 4	 4 1 -2 2 1 4 2 2 -2 2 -4 -1 2 2 1 4
 10 0 6 -3 0 10 4 -8 6 4 10 -5 -3 -8 -5 10	 4 0 -2 0 0 4 -3 3 -2 -3 4 -3 0 3 3 4	 4 0 1 -2 0 4 0 3 1 0 4 -2 -2 -3 2 4	 4 0 -2 1 0 4 -2 1 -2 2 4 -2 1 1 2 4	 12 3 -9 6 3 12 -9 6 -9 9 12 -8 6 6 -8 12	 4 0 -2 0 0 4 3 0 -2 -3 4 -1 0 0 1 4
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 4 -3 -2 1 -3 4 -2 2 -2 2 4 2 1 -2 2 4	 2 0 1 -1 0 2 -1 -1 -1 -1 2 -1 -1 -1 -2	 5 0 4 -3 0 5 2 4 4 2 5 4 -3 4 4 5	 8 -2 4 -7 -2 8 4 -2 -4 8 2 -7 2 2 8	 10 0 4 -6 0 10 -3 -8 4 -3 10 0 -6 8 0 10	 4 1 1 -2 1 4 2 -2 1 4 2 -2 -2 2 -2 4
 9 0 6 -6 0 9 3 -3 -6 3 9 -1 -6 3 -1 9	 30 9 44 35 9 30 48 46 -44 48 80 -44 35 -44 80 89	 14 -11 -1 -7 -11 14 7 2 -11 7 14 13 -7 2 13 14	 10 0 -6 -3 0 10 -8 4 -6 8 10 -5 3 4 -5 10	 25 9 20 -15 9 25 15 -20 20 15 25 -24 -15 -20 24 25	 2 1 1 -1 1 2 1 -1 -1 2 1 -1 -1 -1 2 2
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 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	 1 0 0 0 0 1 1 1 0 1 1 1 0 1 1 1	 1 a b c a 1 d e b d 1 f c e f 1	$\text{Model } 3$ $a^2 = \frac{100}{18289} = \sqrt{107463}$ $b = 10 = \frac{100}{18289} = \sqrt{107463}$ $d = 10 = \frac{100}{18289} = \sqrt{107463}$		
					

Petr Šimeček. "Gaussian representation of independence models over four random variables".

In: *COMPSTAT conference*. 2006

Consistency certification is hard

Šimeček's Question (2006)

Does every non-empty Gaussian CI model contain a rational point?

Or: can every wrong inference rule be refuted over \mathbb{Q} ?

Consistency certification is hard

Šimeček's Question (2006)

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Or: can every wrong inference rule be refuted over \mathbb{Q} ?

Model M85 *Where:*



$a = \frac{3}{632836} \sqrt{1107463},$
 $b = 10c = \frac{100}{158209} \sqrt{1107463}$
 $d = 10e = \frac{3}{4}, f = \frac{1}{10}$

$$\begin{pmatrix} 1 & -1/17 & -49/51 & -7/17 \\ -1/17 & 1 & 1/3 & 1/7 \\ -49/51 & 1/3 & 1 & 3/7 \\ -7/17 & 1/7 & 3/7 & 1 \end{pmatrix}$$

Consistency certification is hard

Šimeček's Question (2006)

Does every non-empty Gaussian CI model contain a rational point?

Or: can every wrong inference rule be refuted over \mathbb{Q} ?

Theorem

For every finite real extension \mathbb{K} of \mathbb{Q} there exists a CI model \mathcal{M} such that $\mathcal{M} \cap \text{PD}_N(\mathbb{K}) \neq \emptyset$ but $\mathcal{M} \cap \text{PD}_N(\mathbb{L}) = \emptyset$ for all proper subfields $\mathbb{L} \subsetneq \mathbb{K}$.

(Graphical models always have rational points.)

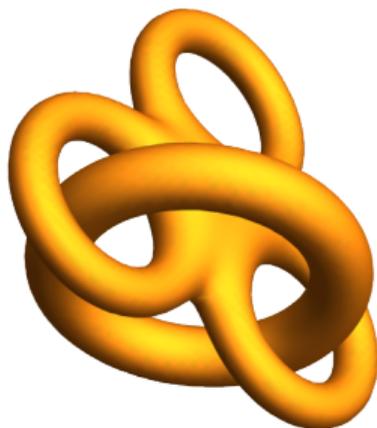
Model topology can be bad

An **oriented** CI model is specified by **sign constraints** on partial correlations.

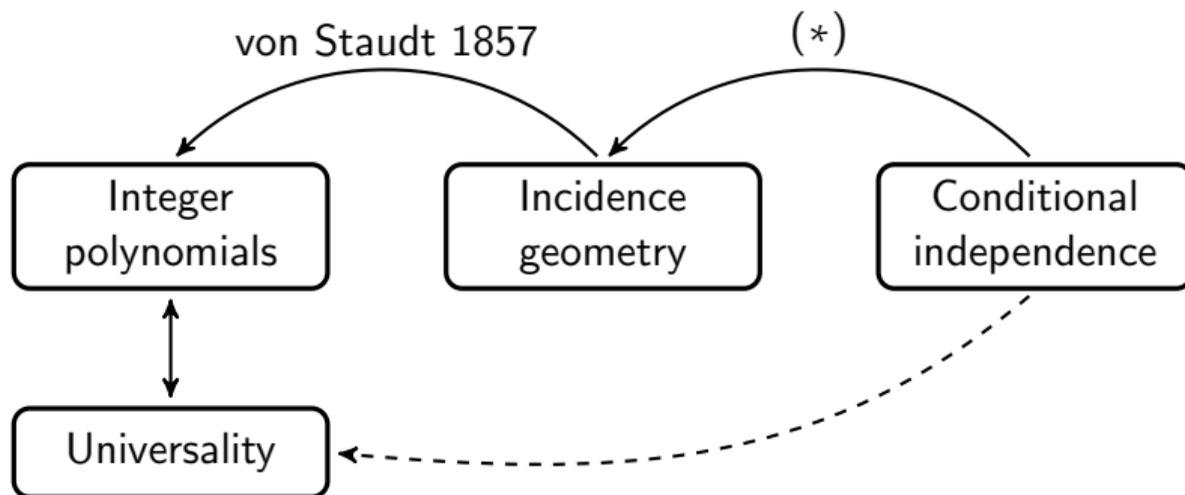
Theorem

For every primary basic semialgebraic set Z there exists an oriented CI model \mathcal{M} which is homotopy-equivalent to Z .

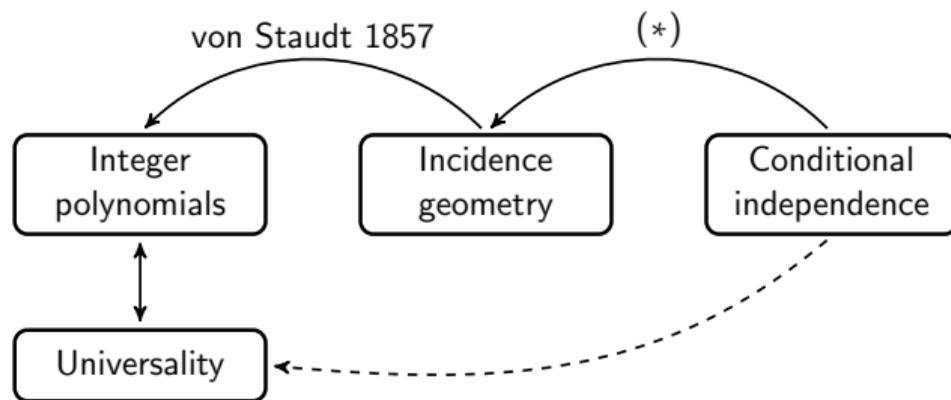
(Graphical models are always contractible.)



Universality theorems



Universality theorems

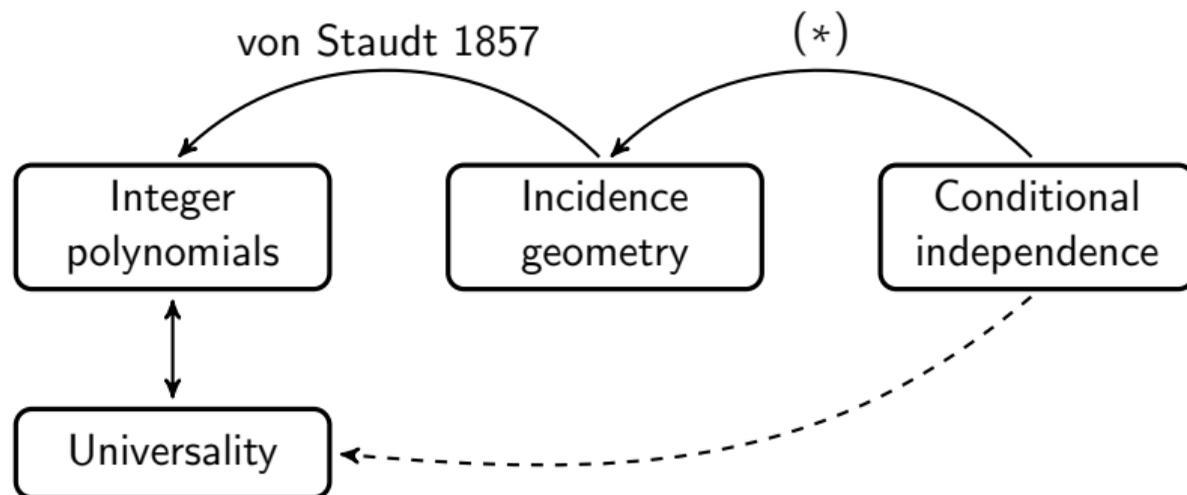


- ▶ Realization spaces of rank-3 matroids
- ▶ Realization spaces of 4-polytopes
- ▶ Nash equilibria of 3-person games
- ▶ Gaussian CI models with conditioning sets of size up to 3 ...

References

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-  Jürgen Bokowski and Bernd Sturmfels. *Computational synthetic geometry*. Vol. 1355. Lecture Notes in Mathematics. Springer, 1989.
-  Ruchira S. Datta. “Universality of Nash equilibria”. In: *Math. Oper. Res.* 28.3 (2003), pp. 424–432. ISSN: 0364-765X.
-  Jürgen Richter-Gebert. *Perspectives on projective geometry. A guided tour through real and complex geometry*. Springer, 2011, pp. xxii + 571.
-  Petr Šimeček. “Gaussian representation of independence models over four random variables”. In: *COMPSTAT conference*. 2006.

Universality theorems: Background



Theorem

To every polynomial system $\{f_i \neq 0\}$ there is a set of CI constraints which has a model over a field \mathbb{K}/\mathbb{Q} if and only if the polynomial system has a solution in \mathbb{K} .

Very special polynomials

$\Sigma[ij|] = x_{ij} \rightarrow$ impose $x_{kl} = x_{km} = x_{lm} = 0$ on a correlation matrix, then:

$$\begin{aligned} \Sigma[ij|klm] &= x_{ij}x_{kk}x_{ll}x_{mm} + x_{im}x_{jm}x_{kl}^2 - x_{im}x_{jl}x_{kl}x_{km} - x_{il}x_{jm}x_{kl}x_{km} + x_{il}x_{jl}x_{km}^2 \\ &\quad - x_{im}x_{jm}x_{kk}x_{ll} + x_{im}x_{jk}x_{km}x_{ll} + x_{ik}x_{jm}x_{km}x_{ll} - x_{ij}x_{km}^2x_{ll} \\ &\quad + x_{im}x_{jl}x_{kk}x_{lm} + x_{il}x_{jm}x_{kk}x_{lm} - x_{im}x_{jk}x_{kl}x_{lm} - x_{ik}x_{jm}x_{kl}x_{lm} \\ &\quad - x_{il}x_{jk}x_{km}x_{lm} - x_{ik}x_{jl}x_{km}x_{lm} + 2x_{ij}x_{kl}x_{km}x_{lm} + x_{ik}x_{jk}x_{lm}^2 \\ &\quad - x_{ij}x_{kk}x_{lm}^2 - x_{il}x_{jl}x_{kk}x_{mm} + x_{il}x_{jk}x_{kl}x_{mm} + x_{ik}x_{jl}x_{kl}x_{mm} \\ &\quad - x_{ij}x_{kl}^2x_{mm} - x_{ik}x_{jk}x_{ll}x_{mm} \\ &= x_{ij} - \sum_{k=l,m} x_{ik}x_{jk} = x_{ij} - \left\langle \left(\begin{matrix} x_{ik} \\ x_{il} \\ x_{im} \end{matrix} \right), \left(\begin{matrix} x_{jk} \\ x_{jl} \\ x_{jm} \end{matrix} \right) \right\rangle. \end{aligned}$$

The rest is 19th century projective geometry. Keyword: *von Staudt constructions*.

Covariance matrix simulating a projective plane

$$\begin{array}{c}
 p_1 \\
 \vdots \\
 p_n \\
 l_1 \\
 \vdots \\
 l_m \\
 x \\
 y \\
 z
 \end{array}
 \left(
 \begin{array}{ccc|ccc|ccc}
 p_1 & \dots & p_n & l_1 & \dots & l_m & x & y & z \\
 p_1^* & & \langle p, p' \rangle & & & & p_1^x & p_1^y & p_1^z \\
 \vdots & \ddots & & & \langle p, l \rangle & & \vdots & & \\
 \langle p', p \rangle & & p_n^* & & & & p_n^x & p_n^y & p_n^z \\
 \hline
 & & & l_1^* & & \langle l, l' \rangle & l_1^x & l_1^y & l_1^z \\
 & \langle l, p \rangle & & & \ddots & & \vdots & & \\
 \langle l', l \rangle & & & & & l_m^* & l_m^x & l_m^y & l_m^z \\
 \hline
 p_1^x & & p_n^x & l_1^x & & l_m^x & x^* & 0 & 0 \\
 p_1^y & \dots & p_n^y & l_1^y & \dots & l_m^y & 0 & y^* & 0 \\
 p_1^z & & p_n^z & l_1^z & & l_m^z & 0 & 0 & z^*
 \end{array}
 \right)$$