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The Gaussian CI inference problem

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Consider random variables $(\xi_i)_{i \in N}$. The conditional independence (CI) statement $\xi_i \perp \!\!\! \perp \xi_j \mid \xi_K$ conveys, informally, that if ξ_K is known, then learning the value of ξ_i does not give any information about ξ_i .



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Example: Let c_1 and c_2 be two independent coins and b a bell which rings if and only if c_1 and c_2 land with the same side up. What is the conditional independence relation of the system (c_1, c_2, b) of random variables?



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Example: Let c_1 and c_2 be two independent coins and b a bell which rings if and only if c_1 and c_2 land with the same side up. What is the conditional independence relation of the system (c_1, c_2, b) of random variables? $\rightarrow c_1 \perp c_2$ and $\neg (c_1 \perp c_2 \mid b)$ and ...



Let the random vector be normally distributed: $(\xi_i)_{i \in N} \sim \mathcal{N}(\mu, \Sigma)$.

Definition

The polynomial $\Sigma[K] := \det \Sigma_{K,K}$ is a *principal minor* of Σ and $\Sigma[ij|K] := \det \Sigma_{iK,jK}$ is an *almost-principal minor*.

If Σ is positive-definite, then $\Sigma[K] > 0$, and $\xi_i \perp \xi_j \mid \xi_K$ holds if and only if $\Sigma[ij \mid K] = 0$.



Almost-principal minors

$$\begin{split} & \Sigma[ij|k] = x_{ij} \\ & \Sigma[ij|k] = x_{ij} x_{kk} - x_{ik} x_{jk} \\ & \Sigma[ij|kl] = x_{ij} x_{kk} x_{ll} - x_{il} x_{jl} x_{kk} + x_{il} x_{jk} x_{kl} + x_{ik} x_{jl} x_{kl} - x_{ij} x_{kl}^2 - x_{ik} x_{jk} x_{ll} \\ & \Sigma[ij|klm] = x_{ij} x_{kk} x_{ll} x_{mm} + x_{im} x_{jm} x_{kl}^2 - x_{im} x_{jl} x_{kl} x_{km} - x_{il} x_{jm} x_{kl} x_{km} + x_{il} x_{jl} x_{km}^2 \\ & - x_{im} x_{jm} x_{kk} x_{ll} + x_{im} x_{jk} x_{km} x_{ll} + x_{ik} x_{jm} x_{km} x_{ll} - x_{ij} x_{km}^2 x_{ll} \\ & + x_{im} x_{jl} x_{kk} x_{lm} + x_{il} x_{jm} x_{kk} x_{lm} - x_{im} x_{jk} x_{kl} x_{lm} - x_{ik} x_{jm} x_{kl} x_{lm} \\ & - x_{il} x_{jk} x_{km} x_{lm} - x_{ik} x_{jl} x_{km} x_{lm} + 2 x_{ij} x_{kl} x_{km} x_{lm} + x_{ik} x_{jl} x_{kl} x_{mm} \\ & - x_{ij} x_{kk} x_{lm}^2 - x_{il} x_{jl} x_{kk} x_{mm} + x_{il} x_{jk} x_{kl} x_{mm} + x_{ik} x_{jl} x_{kl} x_{mm} \\ & - x_{ij} x_{kl}^2 x_{mm} - x_{ik} x_{jk} x_{ll} x_{mm} \\ & \vdots \end{split}$$



Gaussian CI models

Definition

A *CI constraint* is a CI statement $\xi_i \perp \!\!\! \perp \xi_j \mid \xi_K$ or its negation $\neg(\xi_i \perp \!\!\! \perp \xi_j \mid \xi_K)$. They are algebraic conditions on the entries of Σ , equivalent to vanishing or non-vanishing of the almost-principal minors $\Sigma[ij|K]$.

Definition

The *model* of a set of CI constraints is the set of all positive-definite matrices which satisfy the constraints.



Gaussian CI models

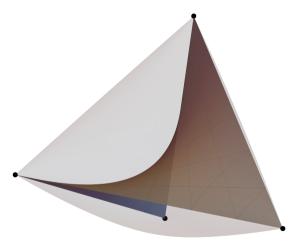


Figure: Model of $\Sigma[12|3] = 0$ in the space of 3×3 correlation matrices.



Models and inference

Consider two sets of CI statements \mathcal{P} and \mathcal{Q} :

$$\bigwedge \mathcal{P} \Rightarrow \bigvee \mathcal{Q}$$



Models and inference

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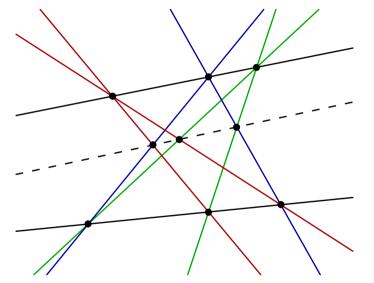
Models and inference

Consider two sets of CI statements \mathcal{P} and \mathcal{Q} :

Reasoning about relevance statements in normally distributed random variables is the same as reasoning about the vanishing of very special kinds of determinants on very special kinds of varieties inside the positive-definite matrices.



For geometers: conditional independence ≈ collinearity





Examples of CI inference

Consider a general positive-definite 3×3 correlation matrix

$$\Sigma = \begin{pmatrix} 1 & a & b \\ a & 1 & c \\ b & c & 1 \end{pmatrix}.$$

• If $\Sigma[12|3] = a - bc$ and $\Sigma[13|] = b$ vanish, then $\Sigma[12|] = a$ and $\Sigma[13|2] = b - ac$ must vanish as well:

$$(12|3) \wedge (13|) \Rightarrow (12|) \wedge (13|2).$$



Examples of CI inference

$$\Sigma = \begin{pmatrix} 1 & a & b \\ a & 1 & c \\ b & c & 1 \end{pmatrix}$$

• If $\Sigma[12|] = a$ and $\Sigma[12|3] = a - bc$ vanish, then $bc = \Sigma[13|] \cdot \Sigma[23|]$ must vanish:

$$(12|) \land (12|3) \Rightarrow (13|) \lor (23|).$$





Rational points on CI models

Šimeček's Question (2006)

Does every non-empty Gaussian CI model contain a rational point?

Or: can every wrong inference rule be refuted over \mathbb{Q} ?



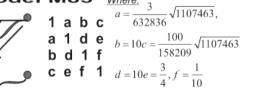
Rational points on CI models

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Model M85



$$\begin{pmatrix} 1 & -1/17 & -49/51 & -7/17 \\ -1/17 & 1 & 1/3 & 1/7 \\ -49/51 & 1/3 & 1 & 3/7 \\ -7/17 & 1/7 & 3/7 & 1 \end{pmatrix}$$



Complexity bounds from real geometry

Let $f_i \in \mathbb{Z}[t_1, \dots, t_k]$ be integer polynomials in finitely many variables.

Theorem (Tarski's transfer principle)

If a polynomial system $\{f_i \bowtie_i 0\}$, where $\bowtie_i \in \{=, \neq, <, \leq, \geq, >\}$, has a solution over \mathbb{R} , then it has a solution in a finite real extension of \mathbb{Q} .

 \rightarrow If $\wedge \mathcal{P} \Rightarrow \vee \mathcal{Q}$ is false, there exists a counterexample matrix Σ with algebraic entries.

 $(12|) \land (12|3) \Rightarrow (13|)$ is false and a counterexample is

$$\begin{pmatrix} 1 & 0 & \frac{1}{2} \\ 0 & 1 & 0 \\ \frac{1}{2} & 0 & 1 \end{pmatrix}.$$



Complexity bounds from real geometry

Let $F, f_i, g_j \in \mathbb{Z}[t_1, \dots, t_k]$ be integer polynomials in finitely many variables.

Theorem (Positivstellensatz)

A polynomial F vanishes on the basic semialgebraic set $\{f_i = 0, g_j \ge 0\}$ if and only if $-F^{2m} \in \text{ideal}(f_i) + \text{cone}(g_j)$ for m large enough.

 \rightarrow If $\land \mathcal{P} \Rightarrow \lor \mathcal{Q}$ is true, there exists an algebraic proof for it with rational coefficients.

 $(12|) \land (12|3) \Rightarrow (13|) \lor (23|)$ is true and a proof is the polynomial identity

$$\Sigma[13|] \cdot \Sigma[23|] = \Sigma[3] \cdot \Sigma[12|] - \Sigma[12|3].$$

The associated decision problem is the existential theory of the reals.



Universality theorems

Theorem (B. 2021)

For every finite real extension \mathbb{K}/\mathbb{Q} there exists a Gaussian CI model $\mathcal{M}_{\mathbb{K}}$ such that: for every \mathbb{L}/\mathbb{Q} , $\mathcal{M}_{\mathbb{K}}$ has an \mathbb{L} -rational point if and only if $\mathbb{K} \subseteq \mathbb{L}$.

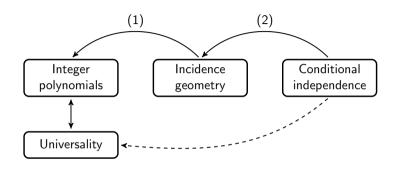
→ The answer to Šimeček's question is **NO**.

Theorem (B. 2021)

The problem of deciding whether a CI inference formula is valid for all Gaussian distributions is polynomial-time equivalent to the existential theory of the reals.



Proof sketch



Theorem

To every polynomial system $\{f_i \bowtie 0\}$ one can compute a polynomially-sized set of CI constraints which has a model over a real algebraic extension \mathbb{K}/\mathbb{Q} if and only if the polynomial system has a solution in \mathbb{K} .

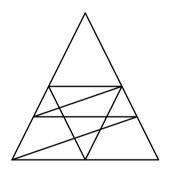


(1) Algebra ⊆ Synthetic geometry

Point and line configuration for the equation $x^2 - 2 = 0$.

The configuration is specified by incidences between points and lines and also the parallelities of lines.

It is realizable over $\mathbb{Q}(\sqrt{2})$ but not over \mathbb{Q} .



Keyword for the general technique: von Staudt constructions (1857).



(2) Synthetic geometry ⊆ Gaussian CI

$$\begin{split} & \Sigma[ij|] = x_{ij} \rightarrow \text{impose } x_{kl} = x_{km} = x_{lm} = 0 \text{ on a correlation matrix, then:} \\ & \Sigma[ij|klm] = x_{ij} \times_{kk} \times_{ll} \times_{mm} + x_{im} \times_{jm} \underline{\times_{kl}}^2 - x_{im} \times_{jl} \underline{\times_{kl} \times_{km}} - x_{il} \times_{jm} \underline{\times_{kl} \times_{km}} + x_{il} \times_{jl} \underline{\times_{km}}^2 \\ & - x_{im} x_{jm} \times_{kk} \times_{ll} + x_{im} x_{jk} \underline{\times_{km}} \times_{ll} + x_{ik} x_{jm} \underline{\times_{km}} \times_{ll} - x_{ij} \underline{\times_{km}}^2 \times_{ll} \\ & + x_{im} x_{jl} \times_{kk} \underline{\times_{lm}} + x_{il} x_{jm} \underline{\times_{kk}} \underline{\times_{lm}} - x_{im} x_{jk} \underline{\times_{kl} \times_{lm}} - x_{ik} x_{jm} \underline{\times_{kl} \times_{lm}} \\ & - x_{il} x_{jk} \underline{\times_{km}} \underline{\times_{lm}} - x_{ik} x_{jl} \underline{\times_{km}} \underline{\times_{lm}} + 2 x_{ij} \underline{\times_{kl} \times_{km}} \underline{\times_{lm}} + x_{ik} x_{jk} \underline{\times_{lm}} \\ & - x_{ij} x_{kk} \underline{\times_{lm}} - x_{il} x_{jl} \underline{\times_{kk}} \underline{\times_{mm}} + x_{il} x_{jk} \underline{\times_{kl}} \underline{\times_{mm}} + x_{ik} x_{jl} \underline{\times_{kl}} \underline{\times_{mm}} \\ & - x_{ij} \underline{\times_{kl}}^2 \underline{\times_{mm}} - x_{ik} x_{jk} \underline{\times_{ll}} \underline{\times_{mm}} \\ & - x_{ij} \underline{\times_{kl}}^2 \underline{\times_{mm}} - x_{ik} x_{jk} \underline{\times_{ll}} \underline{\times_{mm}} \\ & = x_{ij} - \sum_{t=k,l,m} x_{it} x_{jt} = x_{ij} - \left(\begin{pmatrix} x_{ik} \\ x_{il} \\ x_{im} \end{pmatrix}, \begin{pmatrix} x_{jk} \\ x_{jm} \\ x_{jm} \end{pmatrix} \right). \end{split}$$



Incidence relation in a CI model

	p_1		p_n	I_1		I_m	×	У	z
p_1	p_1^*		$\langle p,p' \rangle$				p_1^{\times}	p_1^y	p_1^z
÷		٠.			$\langle p,\ell angle$			÷	
p_n	$\langle p',p \rangle$		p_n^*				p_n^{\times}	p_n^y	p_n^z
I_1				ℓ_1^*		$\langle \ell, \ell' \rangle$	ℓ_{1}^{x}	ℓ_1^y	ℓ_1^z
:	İ	$\langle \ell, p \rangle$			٠.			÷	
I_m	·			$\langle \ell', \ell \rangle$		$\ell_{m m}^{m *}$	ℓ_{m}^{\times}	ℓ_m^y	ℓ_m^z
×	$p_1^{\scriptscriptstyle X}$		p_n^{\times}	ℓ_1^{x}		$\ell_{m{m}}^{m{ imes}}$ $\ell_{m{m}}^{m{y}}$	1	0	0
У	p_1^y	•••	p_n^y	ℓ_1^y	•••		0	1	0
z	p_1^z		p_n^z	ℓ_1^z		$\ell_{\it m}^{\it z}$	0	0	1 <i>J</i>



Approximations to the inference problem



Approximations to the inference problem

Theorem (Matúš 2005)

The following relations hold for every symmetric matrix Σ :

$$\Sigma[kL] \cdot \Sigma[ij|L] = \Sigma[L] \cdot \Sigma[ij|kL] + \Sigma[ik|L] \cdot \Sigma[jk|L].$$

These relations define essential geometric properties of symmetric matrices in principal and almost-principal minor coordinates. Study their combinatorics!



The Gaussian CI configuration space

$$\Sigma[kL] \cdot \Sigma[ij|L] = \Sigma[L] \cdot \Sigma[ij|kL] + \Sigma[ik|L] \cdot \Sigma[jk|L]$$

The Gaussian CI configuration space $\mathscr{G} \subseteq \mathbb{R}^{2^n} \times \mathbb{R}^{\binom{n}{2}2^{n-2}}$ consists of all vectors of principal and almost-principal minors of $\Sigma \in \mathsf{PD}_n$.



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Very wasteful encoding of a matrix, but this creates simple and useful relations on configuration vectors. The CI structure of Σ is encoded in the zero pattern of $c(\Sigma) \in \mathscr{G}$.



Combinatorial compatibility

$$\Sigma[kL] \cdot \Sigma[ij|L] = \Sigma[L] \cdot \Sigma[ij|kL] + \Sigma[ik|L] \cdot \Sigma[jk|L]$$

Combinatorial compatibility means fulfilling polynomial relations under uncertainty: What if we only knew that all $\Sigma[K] \neq 0$ and whether or not $\Sigma[ij|K] = 0$ for every (ij|K)?



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$$(ij|L) \wedge (ij|kL) \Rightarrow (ik|L) \vee (jk|L)$$
$$(ik|L) \wedge (ij|kL) \Rightarrow (ij|L)$$
$$\vdots$$



Combinatorial compatibility

$$\Sigma[kL] \cdot \Sigma[ij|L] = \Sigma[L] \cdot \Sigma[ij|kL] + \Sigma[ik|L] \cdot \Sigma[jk|L]$$

Combinatorial compatibility means fulfilling polynomial relations under uncertainty: What if we only knew that all $\Sigma[K] \neq 0$ and whether or not $\Sigma[ij|K] = 0$ for every (ij|K)?

$$\begin{aligned} &(ij|L) \quad \wedge (ij|kL) \Rightarrow (ik|L) \vee (jk|L) \\ &(ik|L) \quad \wedge (ij|kL) \Rightarrow (ij|L) \quad \wedge (ik|jL) \\ &(ij|kL) \wedge (ik|jL) \Rightarrow (ij|L) \quad \wedge (ik|L) \\ &(ij|L) \quad \wedge (ik|L) \Rightarrow (ij|kL) \wedge (ik|jL) \end{aligned}$$

This yields the definition of gaussoids.



CI inference via SAT solvers

Since gaussoids have a finite axiomatization, a SAT solver like CaDiCaL can deduce implications under the gaussoid axioms:

$$(12|3) \wedge (12|34) \wedge (24|1) \wedge (34|2)$$

$$\Rightarrow (12|) \wedge (12|4) \wedge (24|) \wedge (24|3) \wedge (24|13) \wedge (34|)$$

These conclusions are valid for all regular Gaussian distributions.



Oriented gaussoids

$$\Sigma[kL] \cdot \Sigma[ij|L] = \Sigma[L] \cdot \Sigma[ij|kL] + \Sigma[ik|L] \cdot \Sigma[jk|L]$$

What if we only knew that all $\operatorname{sgn} \Sigma[K] = +1$ and the value of $\operatorname{sgn} \Sigma[ij|K]$ for every (ij|K)?

$$+(ij|L) \wedge -(ij|kL) \Rightarrow [+(ik|L) \wedge +(jk|L)] \vee [-(ik|L) \wedge -(jk|L)]$$

→ Oriented and orientable gaussoids.



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→ Oriented and orientable gaussoids.

$$\begin{array}{lll} (ij|L) & \wedge (kl|L) \wedge (ik|jlL) \wedge (jl|ikL) \Rightarrow (ik|L) \\ (ij|L) & \wedge (kl|iL) \wedge (kl|jL) \wedge (ij|klL) \Rightarrow (kl|L) \\ (ij|L) & \wedge (jl|kL) \wedge (kl|iL) \wedge (ik|jlL) \Rightarrow (ik|L) \\ (ij|kL) \wedge (ik|lL) \wedge (il|jL) & \Rightarrow (ij|L) \\ (ij|kL) \wedge (ik|lL) \wedge (jl|iL) \wedge (kl|jL) \Rightarrow (ij|L) \\ \end{array}$$



CI inference via SAT solvers II

Using the gaussoid axioms, we find:

$$(12|) \land (13|4) \land (14|5) \land (15|23) \land (23|5) \land (24|135) \land (34|12) \land (35|1) \land (45|2)$$
 \Rightarrow nothing.

The structure on the left is a gaussoid.



CI inference via SAT solvers II

Running the SAT solver CaDiCaL on the definition of oriented gaussoids confirms that their supports satisfy

$$(12|) \land (13|4) \land (14|5) \land (15|23) \land (23|5) \land (24|135) \land (34|12) \land (35|1) \land (45|2)$$

 \Rightarrow everything except $(25|K)$ for all K .

The geometric model is that of a Markov network!



The search for inference rules

Inference rules help characterize the *realizable* CI structures:

- 3-variate: 11 out of 64 by Matúš 2005.
- 4-variate: 629 out of 16777 216 by Lněnička and Matúš 2007.
- 5-variate: *open!* (out of 1208 925 819 614 629 174 706 176)
 - 254 826 gaussoids modulo symmetry
 - 87834 of which are orientable gaussoids
 - 84 908 of which are *selfadhesive* orientable gaussoids.



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Help wanted:

- Use information inequalities and linear programming.
- Tropical approximations and valuated gaussoids.
- Compute algebraic realization spaces.
- Find and certify real solutions to polynomial systems.





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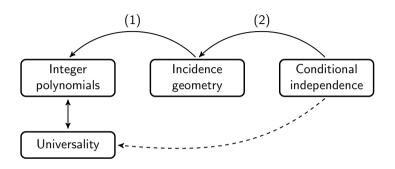
In COMPSTAT conference, 2006.



Proof sketch



Proof sketch



Theorem

To every polynomial system $\{f_i \bowtie 0\}$ one can compute a polynomially-sized set of CI constraints which has a model over a real algebraic extension \mathbb{K}/\mathbb{Q} if and only if the polynomial system has a solution in \mathbb{K} .

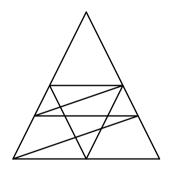


(1) Algebra ⊆ Synthetic geometry

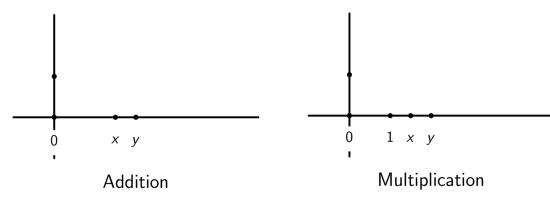
Point and line configuration for the equation $x^2 - 2 = 0$.

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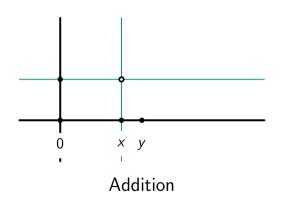
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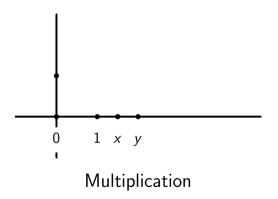




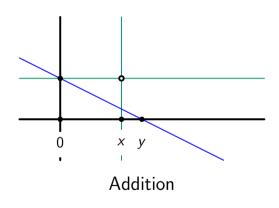


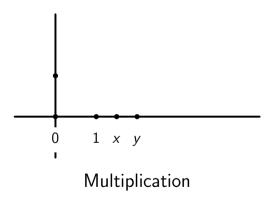




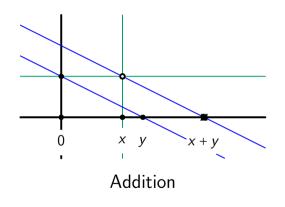


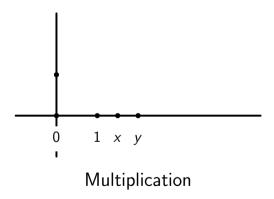




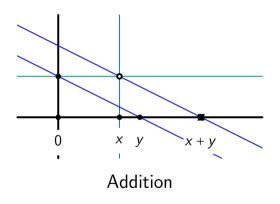


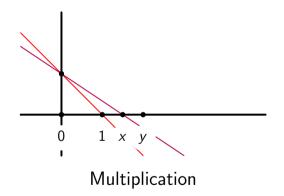




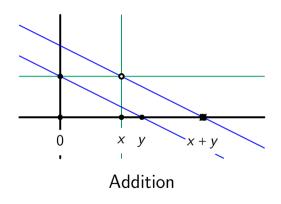


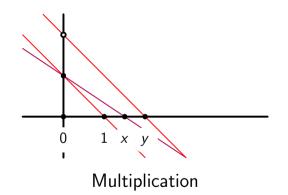




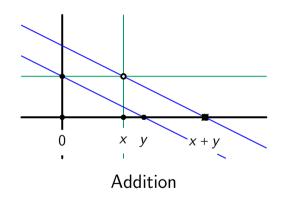


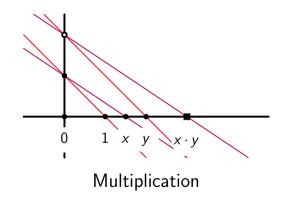






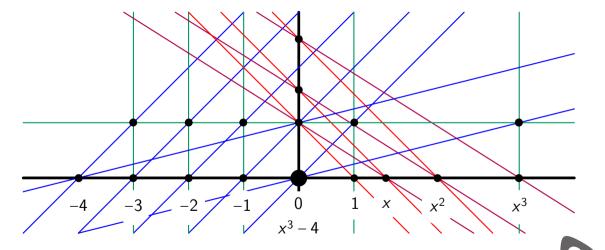








The cube root of 4





$$\begin{split} \Sigma[ij|] &= x_{ij} \rightarrow \text{impose } x_{kl} = x_{km} = x_{lm} = 0 \text{ on a correlation matrix, then:} \\ \Sigma[ij|klm] &= x_{ij} \times_{kk} \times_{ll} \times_{mm} + x_{im} \times_{jm} \underline{x_{kl}^2} - x_{im} \times_{jl} \underline{x_{kl} \times_{km}} - x_{il} \times_{jm} \underline{x_{kl} \times_{km}} + x_{il} \times_{jl} \underline{x_{km}^2} \\ &- x_{im} x_{jm} \times_{kk} \times_{ll} + x_{im} x_{jk} \underline{x_{km}} \times_{ll} + x_{ik} x_{jm} \underline{x_{km}} \times_{ll} - x_{ij} \underline{x_{km}^2} \times_{ll} \\ &+ x_{im} x_{jl} \times_{kk} \underline{x_{lm}} + x_{il} x_{jm} x_{kk} \underline{x_{lm}} - x_{im} x_{jk} \underline{x_{kl} \times_{lm}} - x_{ik} x_{jm} \underline{x_{kl} \times_{lm}} \\ &- x_{il} x_{jk} \underline{x_{km} x_{lm}} - x_{ik} x_{jl} \underline{x_{km} x_{lm}} + 2 x_{ij} \underline{x_{kl} x_{km} x_{lm}} + x_{ik} x_{jk} \underline{x_{lm}^2} \\ &- x_{ij} \underline{x_{kk}} \underline{x_{lm}^2} - x_{il} x_{jl} \underline{x_{kk} x_{mm}} + x_{il} x_{jk} \underline{x_{kl} x_{mm}} + x_{ik} x_{jl} \underline{x_{kl} x_{mm}} \\ &- x_{ij} \underline{x_{kl}^2} \underline{x_{mm}} - x_{ik} x_{jk} \underline{x_{ll} x_{mm}} \\ &= x_{ij} - \sum_{k=k,l,m} x_{ik} x_{jk} = x_{ij} - \left(\begin{pmatrix} x_{ik} \\ x_{il} \\ x_{im} \end{pmatrix}, \begin{pmatrix} x_{jk} \\ x_{jm} \\ x_{jm} \end{pmatrix} \right). \end{split}$$



$$\begin{split} & \Sigma[ij|klm] = 0 \iff \Sigma_{ij} = \langle \Sigma_{i,klm}, \Sigma_{j,klm} \rangle \\ & \Sigma[ij|] = 0 \iff \Sigma_{ij} = 0 \end{split} \iff \Sigma_{i,klm} \perp \Sigma_{j,klm} \end{aligned}$$



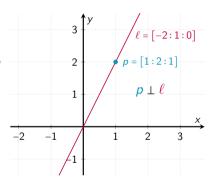
$$\begin{split} & \Sigma[ij|klm] = 0 \iff \Sigma_{ij} = \left\langle \Sigma_{i,klm}, \Sigma_{j,klm} \right\rangle \\ & \Sigma[ij|] = 0 \iff \Sigma_{ij} = 0 \end{split} \iff \Sigma_{i,klm} \perp \Sigma_{j,klm} \end{split}$$

 $p = \sum_{i,klm} = [p_x : p_y : p_z]$ and $\ell = \sum_{j,klm} = [\ell_x : \ell_y : \ell_z]$ are the *homogeneous coordinates* of a point and a line in the projective plane with $p \in \ell^\perp$.



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Incidence relation in a CI model

	p_1		p_n	I_1		I_m	×	у	z
p_1	p_1^*		$\langle p, p' \rangle$				p_1^{\times}	$ ho_1^{\scriptscriptstyle Y}$	p_1^z
:		٠.			$\langle p,\ell angle$			÷	1
p_n	$\langle p',p \rangle$		p_n^*				p_n^{\times}	p_n^y	p_n^z
I_1				ℓ_1^*		$\langle \ell, \ell' \rangle$	ℓ_1^{x}	ℓ_1^y	ℓ_1^z
÷		$\langle \ell, p \rangle$			٠.			÷	İ
I_m				$\langle \ell', \ell \rangle$		$\ell_{m m}^{m *}$	ℓ_{m}^{\times}	ℓ_m^y	ℓ_m^z
×	p_1^{\times}		p_n^{\times}	ℓ_1^{x}		$\ell_{m m}^{m x}$	1	0	0
У	$ ho_1^{\scriptscriptstyle Y}$	•••	p_n^y	ℓ_1^y	•••	ℓ_{m}^{y}	0	1	0
z	p_1^z		p_n^z	ℓ_1^z		ℓ_{m}^{z}	0	0	1 /

